

Lateral Detecting Limit of Underground Imaging Owing To Directivity of Sound Source

音源指向特性による地中埋設物映像化の横方向探査範囲

Ryo Toh^{1†}, Daiki Ando² and Seiichi Motooka¹ (¹Facult. Eng., Chiba Inst. Tech.;
²Graduate School Eng., Chiba Inst. Tech.)
陶良^{1†}, 安藤大樹², 本岡誠一¹ (¹千葉工大 工; ²千葉工大 院)

1. Introduction

Efficient technique for imaging objects buried shallowly underground, such as archaeological exploration and pipeline detection, is expected. Though underground radar is popularly used in civil engineering, in an area with many electrolytes or high moisture in the ground, method using ultrasound is considered to be more efficient. In order to acquire images of underground objects with less error images and high resolution, in the condition of field testing with poor original receiving signals influenced by the large attenuation of high-frequency wave and reflection of multiple unevenness in the ground, a three dimensional imaging method using electromagnetic induction (EMI) type sound source and amplitude correlation synthesis processing (ACSP) method was proposed[1-3]. Up to now, the efficiency of the method is verified, and the lateral resolution of the method is studied experimentally.

Considering the directivity of the EMI sound source[4-5] and the nonlinearity of the ACSP signal processing method, this paper discusses of the lateral detecting limit of the method. The relation between the magnitude of images of multiple underground objects with the directivity of the EMI sound source is studied with experiment and numerical simulation. The imaging results of varies arrangement of multiple underground objects show an approxiamate agreement with the theoretical estimation using the directivity of the sound source. And a lateral detecting limit of about 35° spread angle from the sound source can be concluded for this imaging method.

2. EMI sound source

Fig. 1 shows the structure of the EMI sound source, composed of a two layer flat spiral coil cemented on a Bakelite plate, with an aluminum plate placed under it. The electric energy charged in the capacitor is discharged instantaneously to the coil, and the aluminum plate will be driven by the impulsive electromagnetic repulsion force to radiate an intense impulsive sound into the ground.

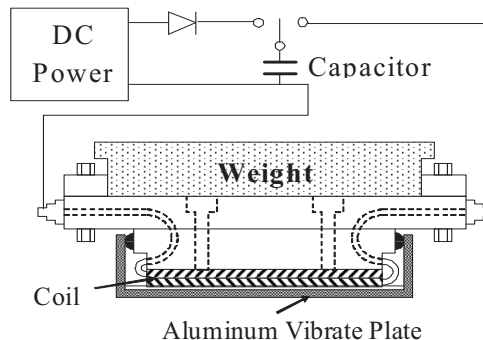


Fig.1 Electromagnetic induction type sound source.

Owing to its particular mechanism, the directivity of radiating sound is different from that of a normal piston vibrating plate, and is given as,

$$R(\theta) = \frac{\mu^2 \cos \theta (\mu^2 - 2 \sin^2 \theta)}{(2\zeta^2 - \mu^2)^2 + 4\zeta^2 \sqrt{\zeta^2 - 1} \sqrt{\zeta^2 - \mu^2}}, \quad (1)$$

where $\zeta = \sin \theta$, $\mu^2 = \frac{2(1-\sigma)}{1-2\sigma}$, and σ is the Poisson's ratio of the ground.

3. Imaging method

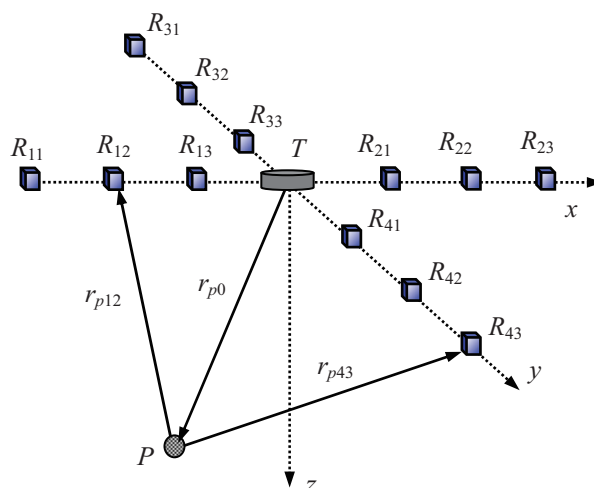


Fig.2 Arrangement of the sound source and receivers.

Fig. 2 shows the arrangement of the sound source and receivers, where the x-y plane denotes the ground surface, as well as an underground point P. With the sound source T as the center of the array, 12 receivers $R_{ij}(i=1, 2, 3, 4; j=1, 2, 3)$ are placed at

[†] liang.tao@it-chiba.ac.jp

